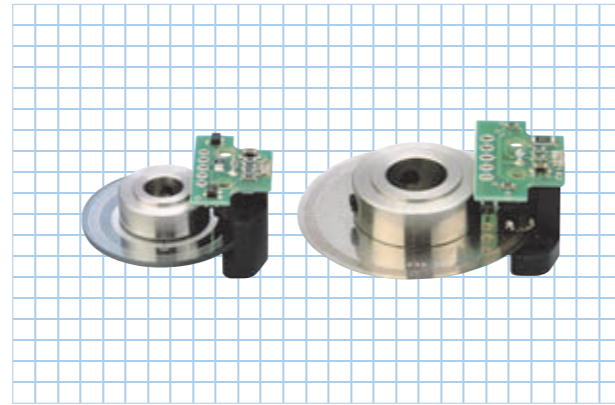
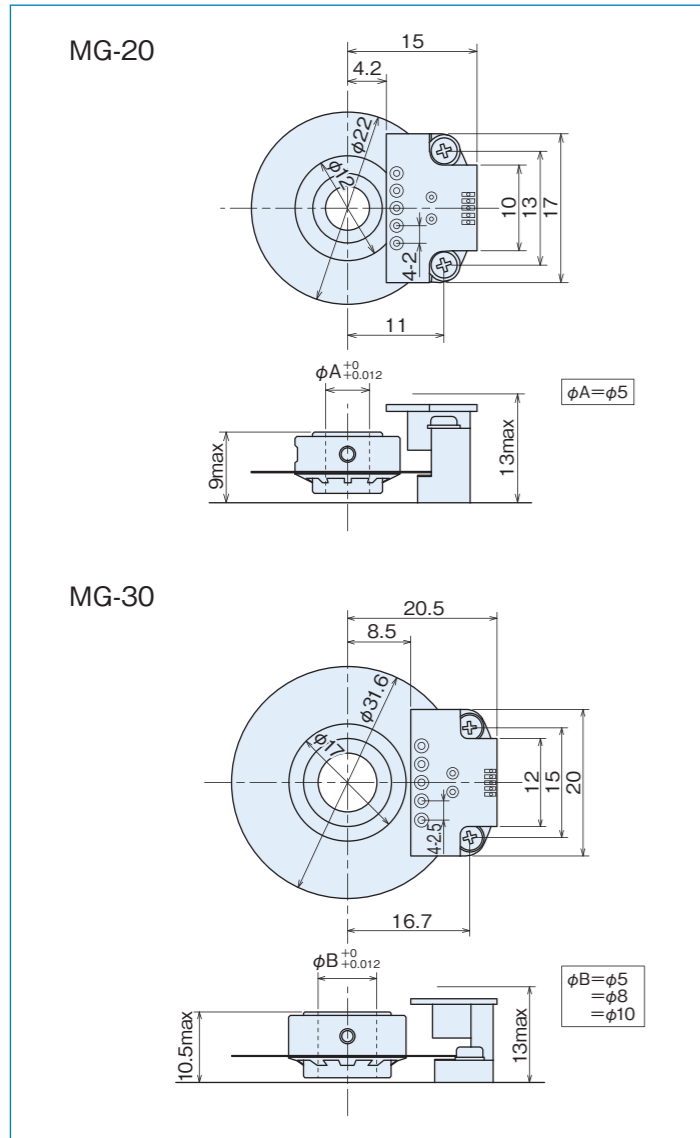


# MG series

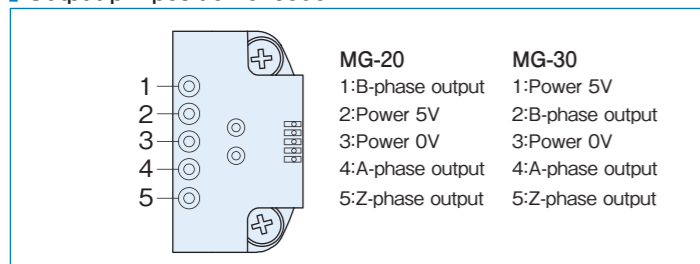
[Module Kit]



## Outside dimensions



## Output pin position encoder



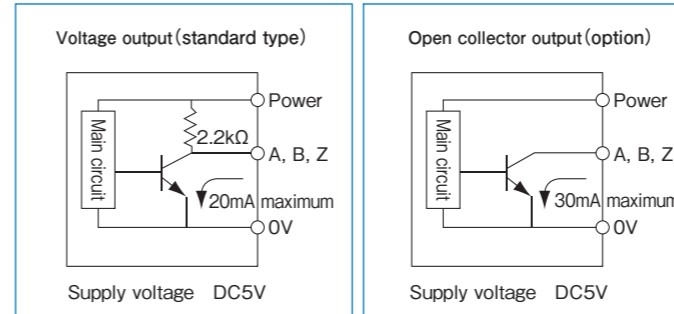
## Specifications

Item	Type name				
	MG-20- Pulse number Output circuit ●No entry=voltage output ●C=open collector output	MG-30- Pulse number Output circuit ●No entry=voltage output ●C=open collector output			
Supply voltage	DC5V±10%				
Current consumption	30mA or less (under no load)				
Detection system	Incremental				
Output pulse number (Standard) [Pulse number/rotation]	100	500	100	600	2,000
	200	512	200	800	
	250	600	250	1,000	
	256	800	300	1,024	
	300	1,000	360	1,200	
	360	1,024	400	1,500	
400	1,200	500	1,800		
Output phase	A, B, Z phase (Z=H)				
Output form	Square Wave				
Output capacity	Sink current:30mA Residual voltage:0.5V or less(at 10mA)				
Maximum response frequency (response pulse number)	100kHz				
Output phase difference	A, B phase difference 90° (T/4±T/8) Z phase T±T/2				
Waveform rise/fall time	2μs or less				
Maximum allowable revolutions (mechanical)	10,000r/min (such that the maximum response frequency is not exceeded)				
Working ambient temperature/ humidity	-10°C~70°C RH35%~90% no dewing				
Storing ambient temperature	-20°C~80°C				
Vibration resistance	Durability 55Hz, double amplitude 1.5mm 2 hours each in X, Y, and Z directions				
Impact resistance	Durability 500m/s <sup>2</sup> (about 50G) 3 times each in X, Y, and Z directions				
I/O terminals	PCB through hole terminals (refer to outside dimensions diagram)				
Mass	10g or less		20g or less		

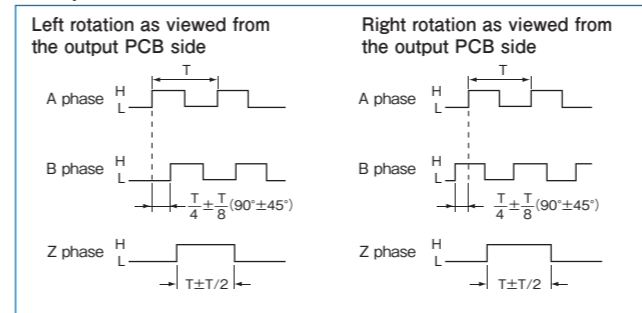
## Allowable change amount of fitting shaft

	MG-20	MG-30	
Pulse number	100~200	250~600	
Pulse number	100~300	400~1,024	
Pulse number		1,200~2,000	
Allowable eccentricity	Radial	±0.05mm	±0.02mm
	Thrust	±0.2mm	±0.1mm

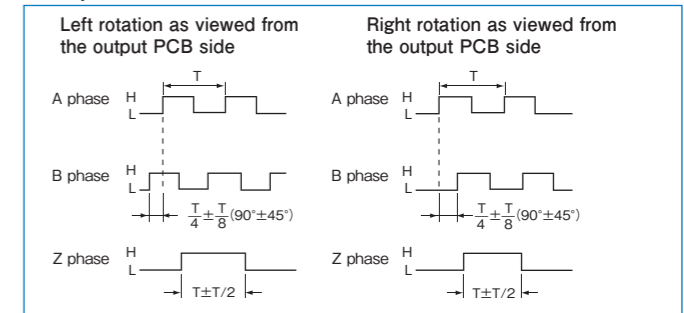
## Output circuit diagram



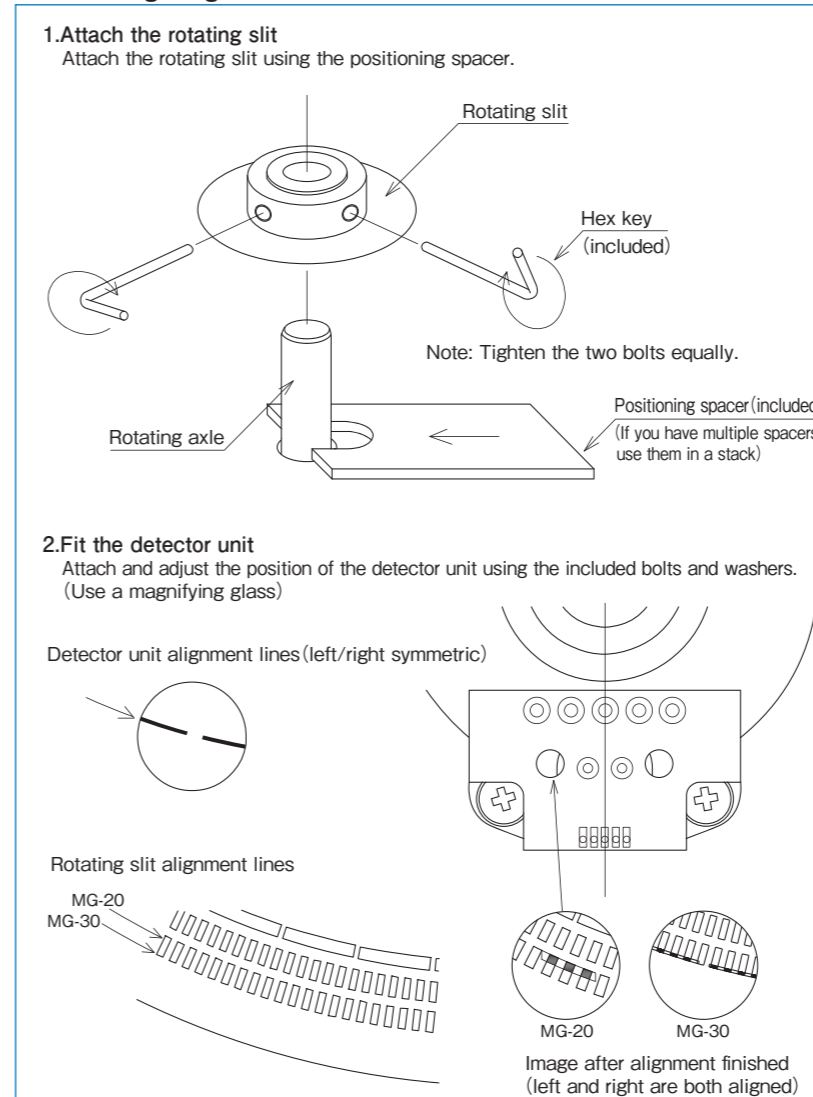
## Output waveforms MG-20



## Output waveforms MG-30



## Assembling image of MG series



## Fitting shaft dimensions

